



AFSCET

*How to think autonomy and safety for the Mars  
manned exploration mission ?*

Stéphane Grès

---

# 1.1. ESTIMATE LEVEL OF SAFETY AND REALITY

---

## ➤ The estimate level of risk (Intrinsecal Safety)

**One accident in 100 flights is somehow « built-in » and may possibly be improved only marginally.**

**(Complex space system as Shuttle)**

## ➤ Reality and figures (Between April 1961 and December 1999)

- **400 human** ventured into orbit around our planet.

- **24 human** on the moon (12 on surface)

- **11 lost their lives** while completing their missions

- **Several dozen were injured or killed** in various flying or training accidents.

## 1.2. KNOWN LIMITS (50 YEARS)

---

- ◆ Experience return underline **structural assembling problems and component limit.**(Challenger and Columbia)
- ◆ Necessity of **retroaction and learning process between astronauts, designers and manufacturers.** (Apollo 1)
- ◆ **Survivability** is in link with formation and training of the crew. Excessive programming rationality could be an undertaking for crisis resolutions. (Apollo 13)
- ◆ **4 & 5 Organisation** seen as the **link between** the project and the actor network is not able to **perceive risks and act in real time (in critical situations).** (Columbia)

# PART 2

---

## BEYOND LIMITS

---

## 2.1. ALREADY KNOWN LIMITS TO OVERPASS

---

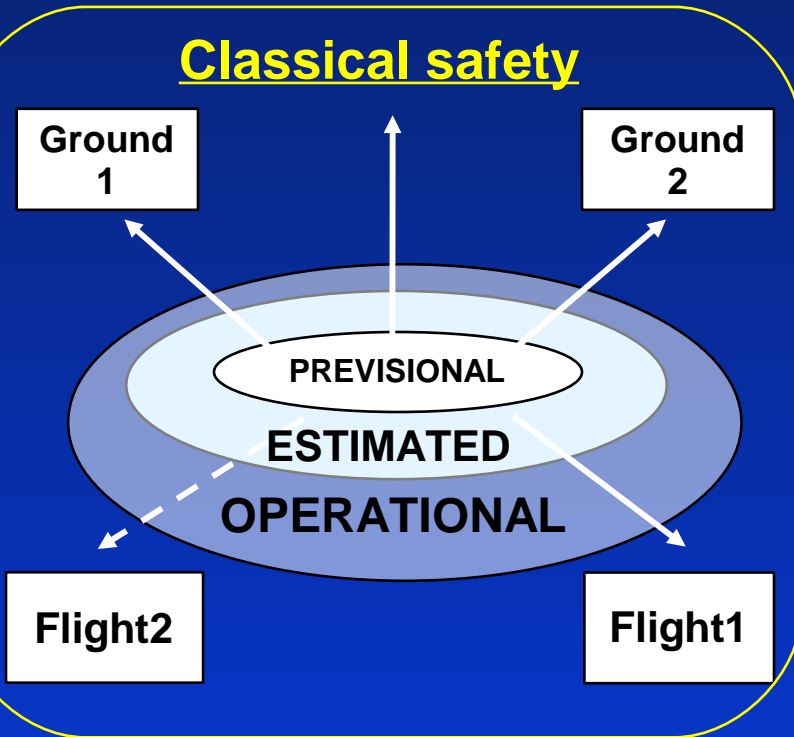
*From system to Men interactions in the early design stage*

- ◆ **Help to reach the profound psychology of Human being in uncertainty and unforeseeable situations (self knowledge and managing relations to differences)**
  - ◆ **Interpersonnal communication and cognition to ameliorate (from the early stage of design to operational stage) project / organization**
-

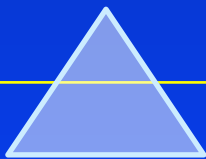
# 2.2. ACTUAL LIMITS IN ORGANIZATION

## 1. BUILDING SAFETY FROM A CENTER

### Classical safety



## 2. RELATIVE FAILS...EXAMPLES (Airbus, Challenger, Tchernobyl...) ✨



## 3. CENTRALISED SAFETY AND/OR DISTRIBUTED SAFETY ?

Needs of renewed path in link with :

➤ Ternarity

(Two centers Earth and ?)

➤ Transition from Pluri to Ternarity

➤ Self-learning aptitude to face dangerous situations



## 2.3. DEFINITION OF SAFETY

---

### Variation of common meaning

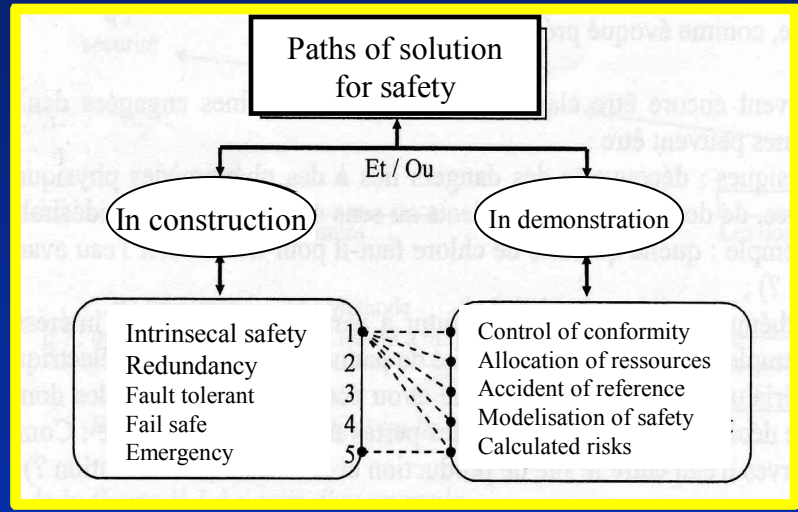
- ◆ Why are there so many accidents ?
- ◆ What to should we do to ameliorate safety ?

### Definition

- ◆ Safety of a system is founded on the organisation of :  
3 sets of garanties: **Physical**, **Mathematical**, **Political**  
ordered in an integrated set of fuzzy datas (or sharp  
datas, nesserarily convincing for prevention and  
protection of accidents.
  - ◆ Accidents of ? : The support exploration system which  
is **unavoidably exposed to danger**.
-

# 2.4. FROM DEFINITION TO MODELISATION

## 3. RESULTS OF MODELISATION



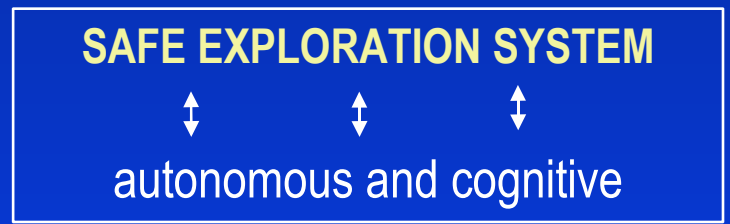
What are we expecting ?

1. Definition
2. Modelisation
3. Paths of solution for safety of the crew

### FIRST STEP



1. DEFINITION



2. MODELISATION



# PART 4

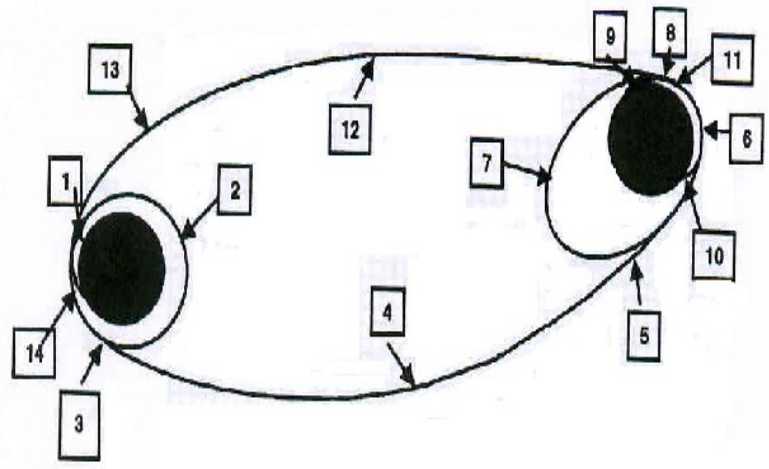
---

**TOWARD THE REFERENTIAL  
FROM PLURI TO TERNARITY  
RELIABLE COMMUNICATION**

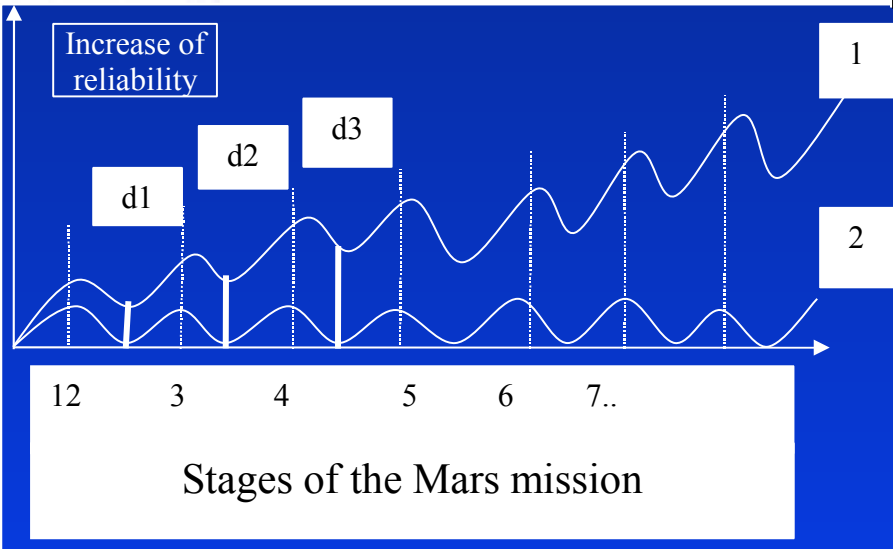
---

# 4.1. BIRTH AND RE-BIRTH OF RELIABILITY

From NASA DRM scénario 1999



1. Launch
2. Earth LEO orbit
3. LEO to Mars Transfer Orbit
4. Mars Transfer Orbit to Mars Orbit
5. Transition to Mars orbit
6. Mars Aerocapture
7. Mars orbit
8. Landing on Mars
9. Mars surface stay
10. Ascent from Mars
11. Mars Orbit to Earth Transfer Orbit
12. Earth transfer
13. Earth orbit
14. Earth Re-entry and landing



1. Increasing curve of Un-reliability  
**(Where we can be afraid from Un-reliability pics)**

2. Theoretical renewal of reliability  
 (Security of security) Mars X Mars

d1, d2, d3 show the gap and deviation which must be conterbalanced with adapted answers (Theoretical <--> Practical)

## *4.2. A NEW FRAME FOR INTERDISCIPLINARITY (2)*

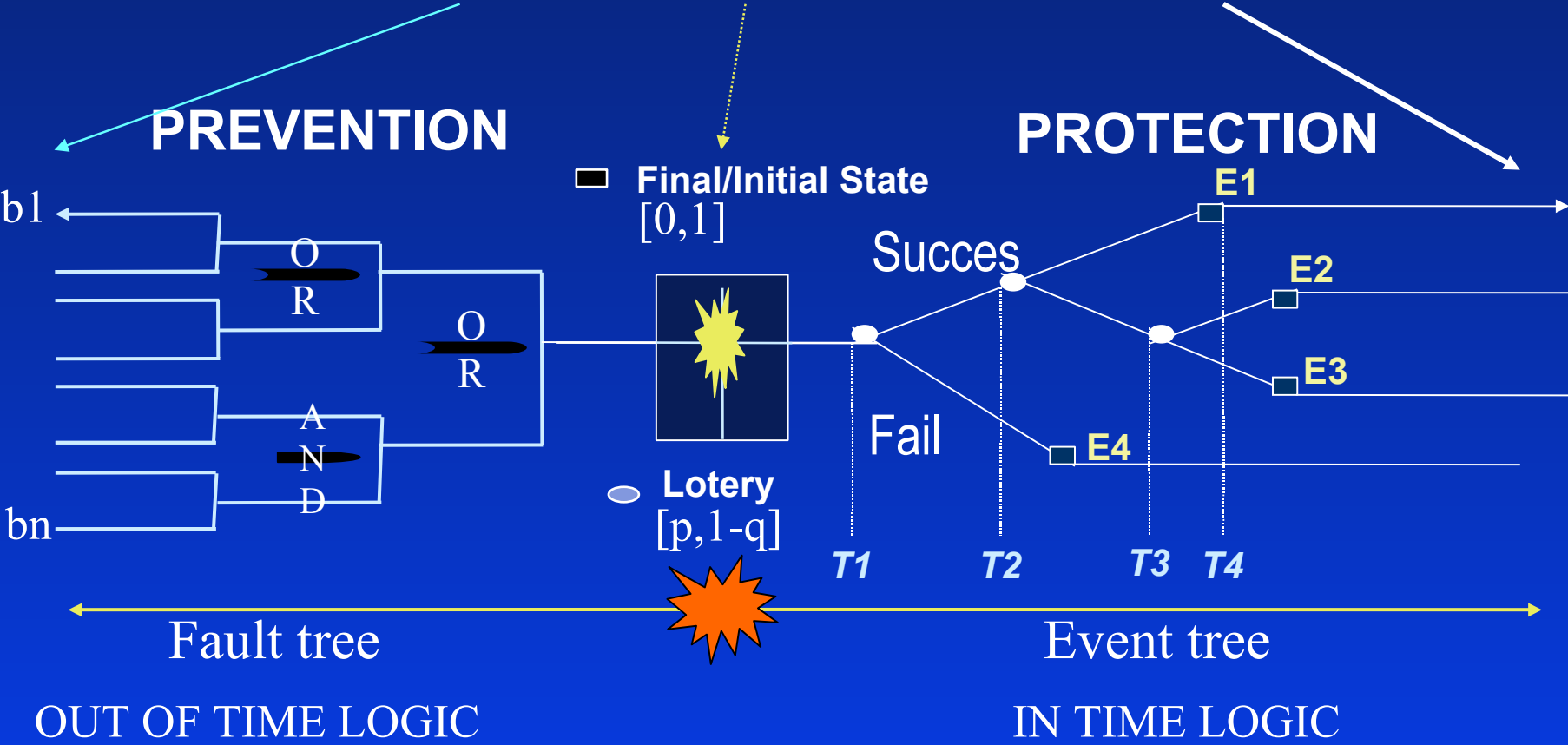
---

- ◆ **Simple** = Easy, not to forget, problems that can be automated
  - ◆ **Complicated** = Know-how, Expertise, Expert Systems, Artificial Intelligence
  - ◆ **Complex** = To solve with distributed cognition, cooperation and autonomy
-

# 4.3. ONTOLOGY OF SAFETY FOR CONTINUOUS RE-BIRTH OF RELIABILITY

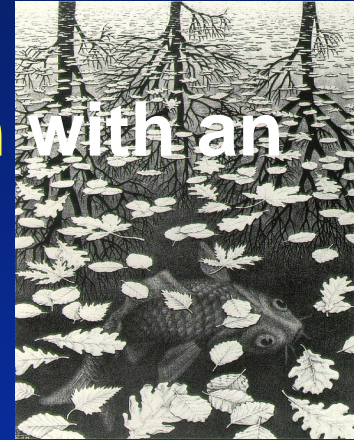
Exploring principles of the un-thinkable and recognition of the living capitalized experiences

## Basic events, Top, Group sets of consequences



# 4.4. A REALITY TO BUILD TOGETHER, (HOW TO MANAGE THE WIDE RISK SPECTRUM ?)

- ◆ To manage and stabilize the **cooperation with an interdisciplinary referential**
- ◆ To constitute a safe validation process :  
Articulation between



Actors System (Human-Human)



Technical System (Machine-Machine)



Information system (Human-machine)



# PART 5

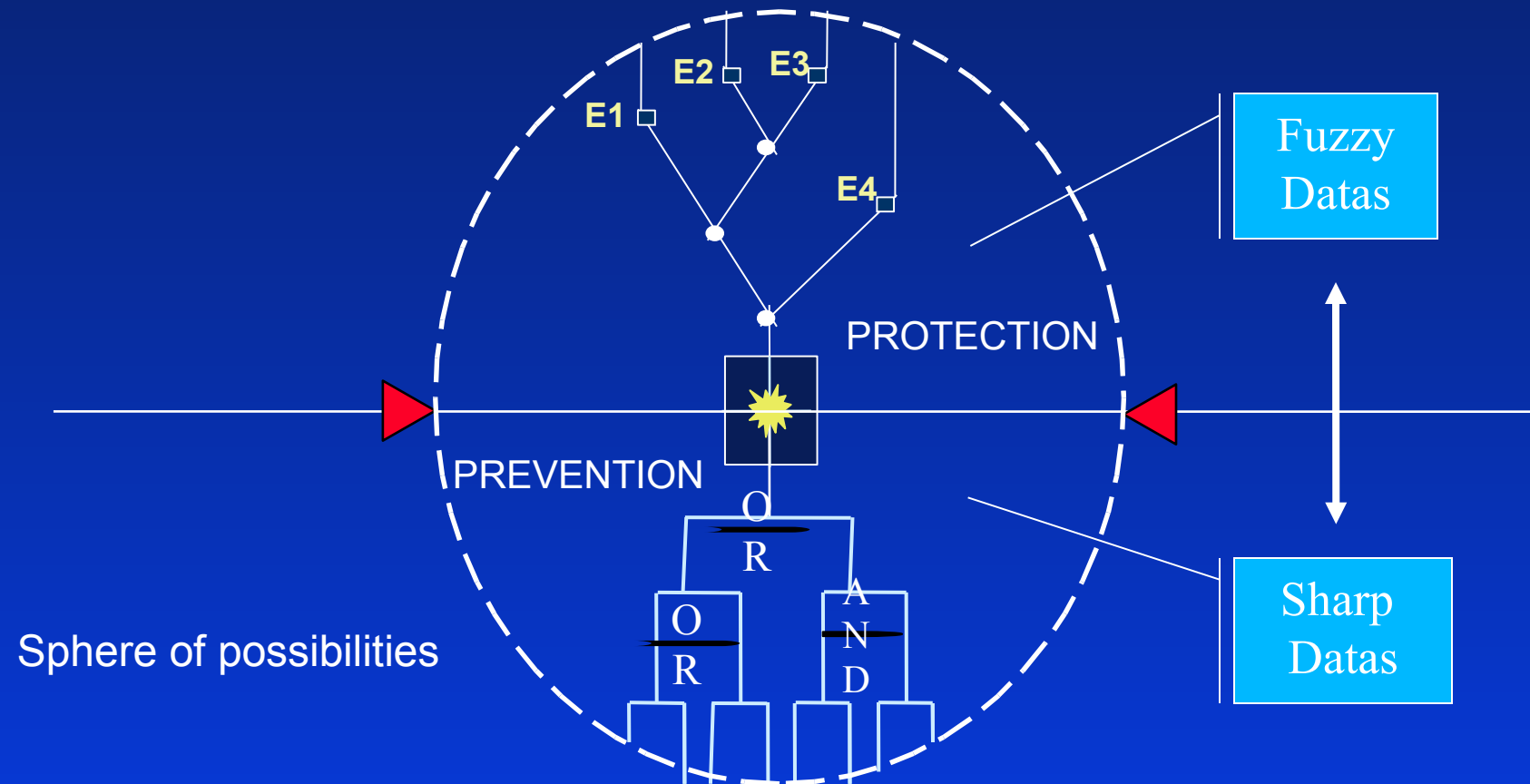
---

## TOWARD THE DECISIONAL INFORMATION SYSTEM FOR SAFETY (D.I.S.S.)

---

# 5.1.D.I.S.S. PRINCIPLES ANTICIPATION OF ACCIDENTS IN REAL TIME

➤ PAST TIME |➤ PRESENT TIME <| FUTURE TIME

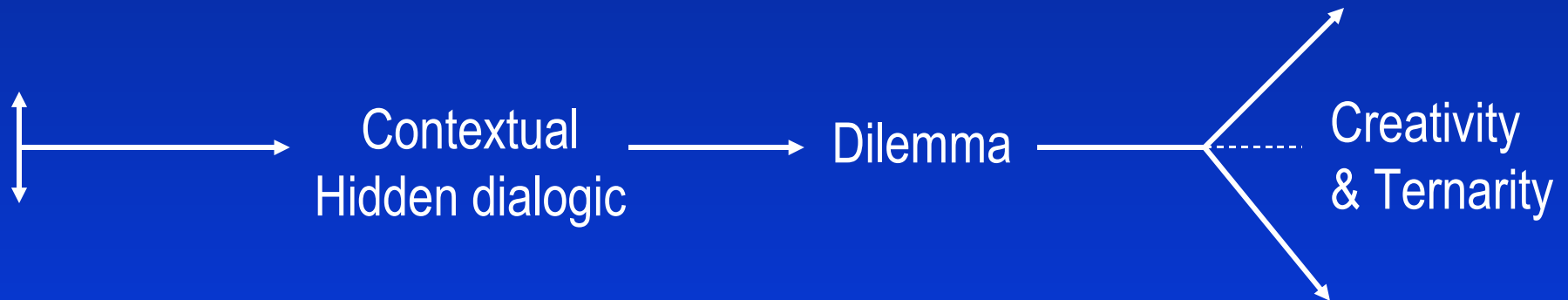


Self-learning process encapsulated at the heart of the exploration system

## 5.2. INTERACTION ORIENTED APPROACH(1)

---

To have an interaction oriented approach can revealed contextual hidden **dialogics** at each steps of the mission. This allow to see **structuration (Birth)** and di-sagregation (Death) of the technological system (which support the Exploration team).





# 5.3. ADVANTAGES

---

We hope to ameliorate safety for Human mission with :

1. **A reliable communication and cognition process**
2. **An embedded anticipation accident capacity**

These 2 contributions have the following advantages :

- Interactions lead by actors **Conscious and Free**
  - Organization build from **individuals to the whole** (relational ethic)
  - Durable cooperation **which tolerate fails and create conditions for self repair.**
  - To be able **to face limits** that overpass half-known or half –unknow horizon of actual knowledge
-